W6series/ Scara Robot

Model **W6-602S**

Operating range Arm length 600mm Joint#3 stroke 200mm

Rated 2kg/Maximum 6kg Payload

Standard cycle time 0.4 sec



Cycle time based on round-trip arch motion (300mm horizontal,25mm vertical) with 2kg payload (path coordinates optimized for maximum speed)

 \pm 0.02mm \pm 0.01mm $\pm 0.01^{\circ}$ Repeatability Joint #1,#2 Joint #3 Joint #4

Parameters of each axis

Joint Content	#1	#2	#3	#4
MAX Operating Speed	6800 mm/s		1100 mm/s	2000°/s
MAX Motion Range	±117.2°	±140°	200mm	±360°
Motor Power Consumption	400W	400W	200W	100W
Joint#3 down force			100N	
Weight	20kg (cables not included)			

Joint #4 allowable moment of inertia, rate 0.01kg·m², maximum 0.12kg·m²

None Need Origin Return Electrical parameters Origin Return Installed wire for customer 26 Pin (D-Sub Connector) φ4mm*2, φ6mm*2

Installed pneumatic tube for customer use

M12*2 Gigabit network interface Visual Interface

Installation Environment Standerd/Clean (Customized)

Outer Dimensions and Motion Range

